



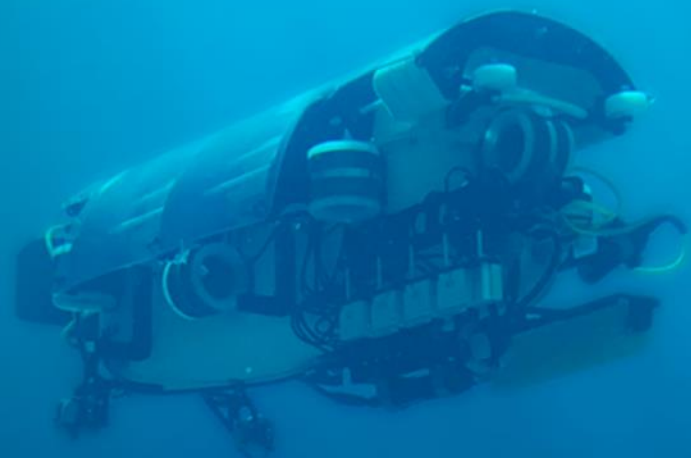
Maximizing Data Quality for In-Service Tank Inspections – Calibrations to Confirmations

Brian Kinsey
Chief Growth Officer
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Advanced Robotics

State of the Art Sensors

High Density Data Acquisition

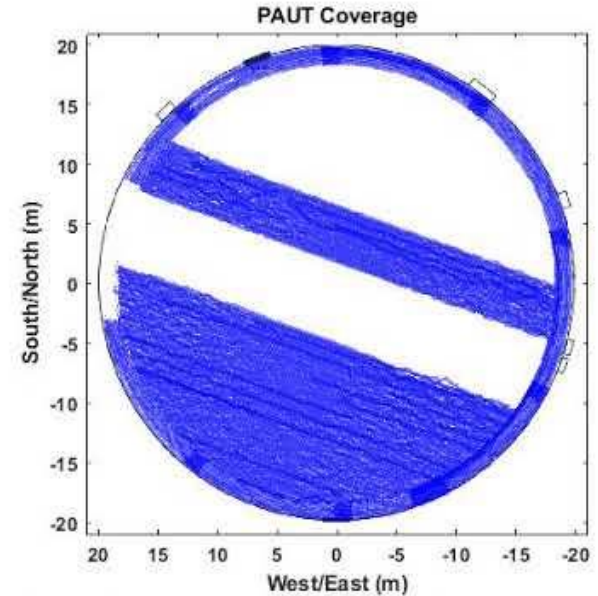


Tank Inspection - The Traditional Approach

- ❑ PROJECT LASTS WEEKS OR MONTHS
- ❑ DRAIN, VENT, CLEAN, WASTE DISPOSAL
- ❑ INSPECT WITH MAGNETIC FLUX LEAKAGE (MFL)
- ❑ VALIDATE WITH SPOT ULTRASONIC (UT)
- ❑ REPAIR *"SINCE IT IS OUT OF SERVICE"*



Square Robot's Tank Inspection Capability



- ❑ Critical 130' Diameter Demineralized Water Tank
- ❑ Tank flowing 5000 gpm in/out during inspection
- ❑ 5 days inspection

Robotics Enable Safe, Informed Efficiency

Environmental, Social, Governance

- Zero confined space entry
- Reduced work at heights
- *Carbon Equivalent releases contained per average tank:
 - Diesel > 5 Tons
 - Gasoline > 20 Tons

*Source - Third Party Verified for 100' diameter tank

Capital Efficiency

- *\$300,000 - +\$2M savings per average out-of-service tank operation
- Proactive risk vs time based inspections

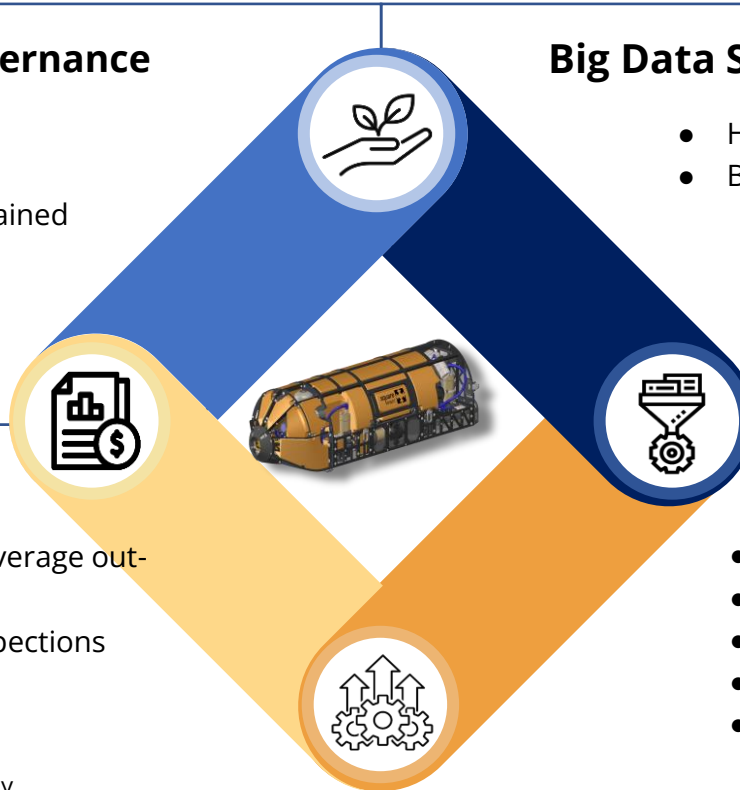
*Source - Solomon Associates 2018 Fuels Study

Big Data Solutions kBytes to tBytes

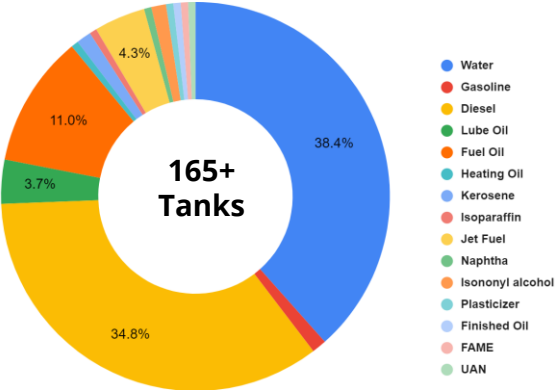
- Hi confidence / hi resolution data
- Big data feed/ advanced processing
 - API 653/ EEMUA 159
 - RBI / EVA / Digital Platforms

Operational Efficiency

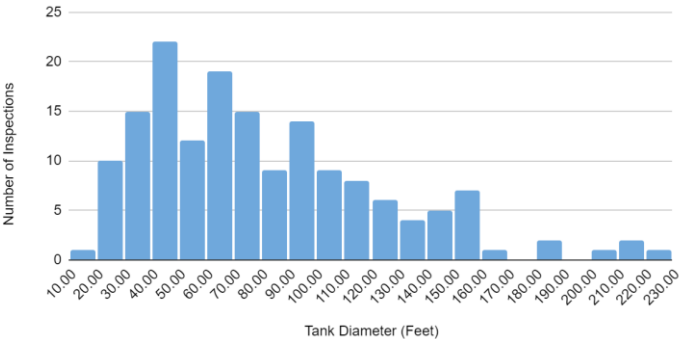
- In- Service Inspection
- Tank utilization
- Extended out of service dates
- Extended tank life
- Predictive repair & maintenance



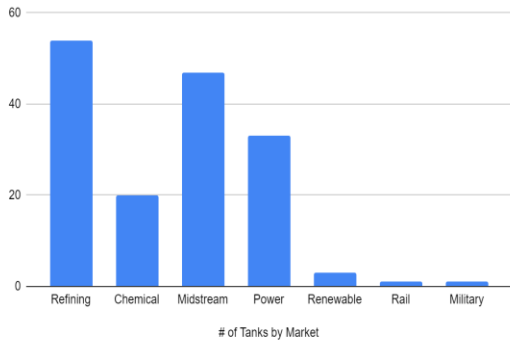
Square Robot Inspection Track Record



Tank Count by Diameter
159 Tanks Inspected through YE2023



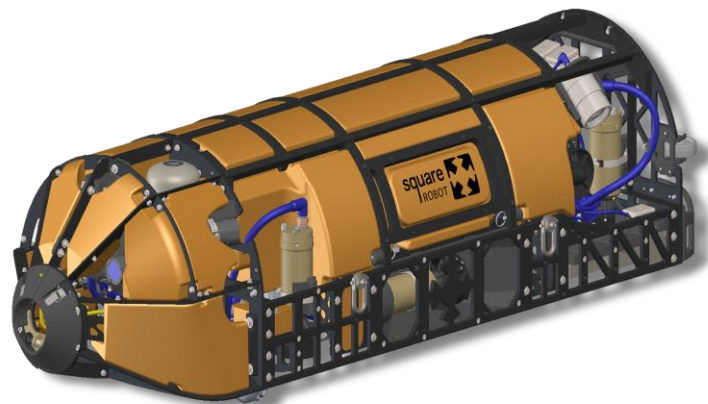
Tank Inspections by Industry



KPI	Count
API 653 Tanks Inspected	>165
PAUT Bottom Coverage (includes obstacles)	60% average (95% max)
Confined Space Labor Hours Saved	100,110 hours (630/tank avg)
CO2 Emissions Equivalent Contained	825,600 lbs(7,800/tank avg)
Tank Utilization	95% - 99%
Cost Savings (assume \$300k x 165 tanks)	\$49 million



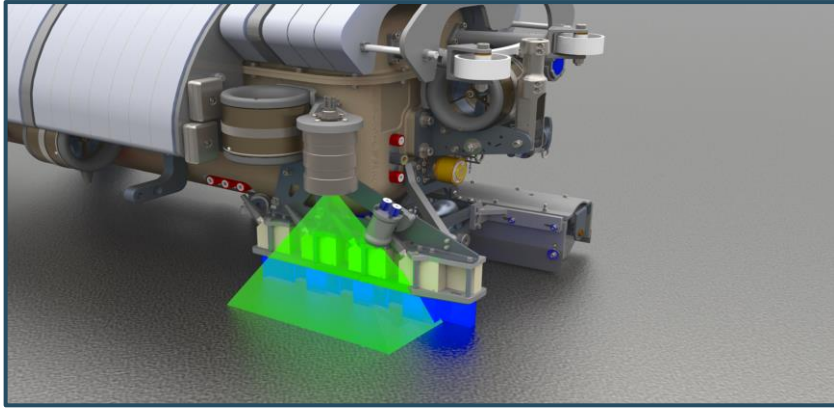
Square Robot's Inspection Capability



SR-3
Autonomous
Submersible
Tank Inspection Robot

Applications		
Launch/Recovery Method	Side Shell or Roof Launch	
Communications	Fiber Optic Tethered	
Tank Type	Fixed, External or Internal Floating Roof	
Product Compatibility	Low/High Flashpoint Products	
PAUT Bottom/Coating Thickness	●	Active
Bottom Settlement Under Load	●	Active
Visuals of Bottom, Shell, Internals	●	Active
PAUT Internal Shell Inspection	●	Active
PAUT Fiberglass Liner Bottoms	●	Active
Internal Roof Seal Inspection	●	In Development
Sediment Thickness Mapping	●	In Development

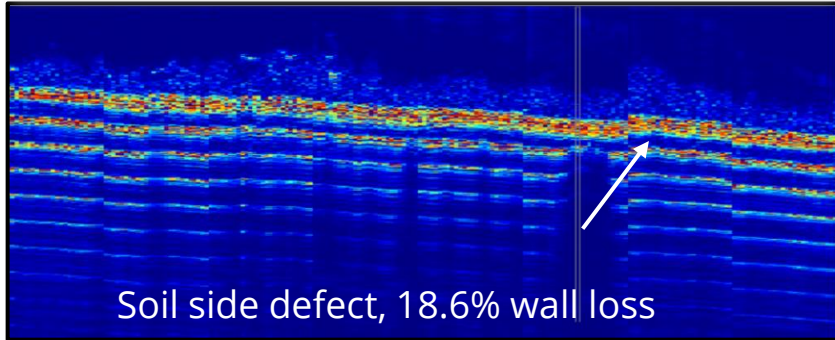
High Resolution Sensors and Navigation



PAUT L-Scan Plate Thickness

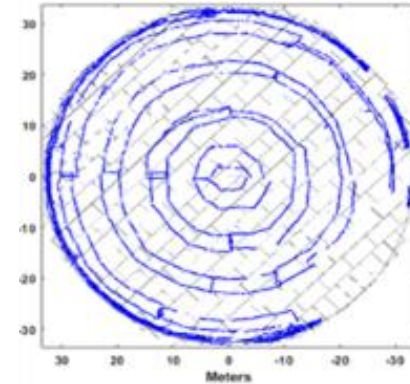
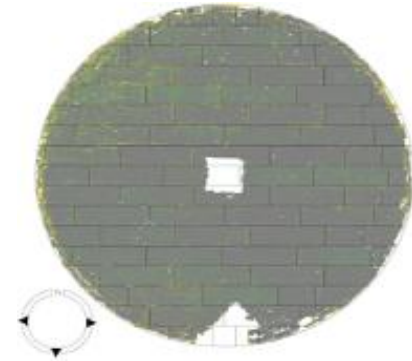
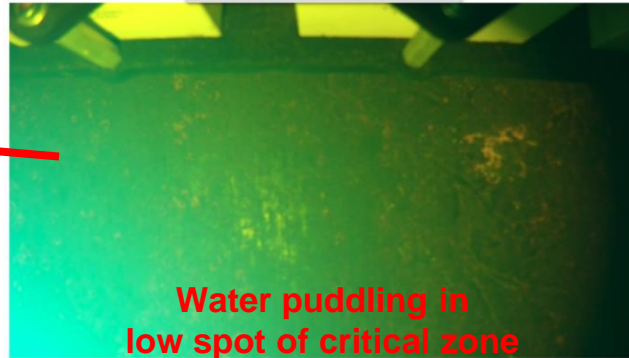
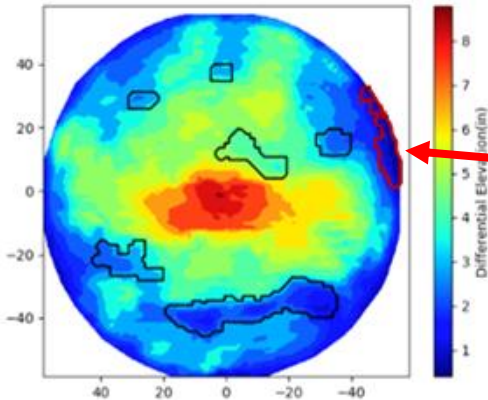


Critical Zone and Water Puddling



API, EEMUA, and Risk Based Inspections

- ❑ Tank Bottom Thickness using Phased Array UT
 - ❑ Differentiate Product and Soil Side
 - ❑ Variety of Epoxy and Fiberglass Liners
- ❑ Tank Shell Thickness using Phased Array UT
- ❑ Internal Visual using 2 onboard video cameras
- ❑ Tank Bottom Settlement *under loaded conditions*



PAUT COVERAGE INCREASES
CONFIDENCE

SR-3 Robot Roof Launch Approach

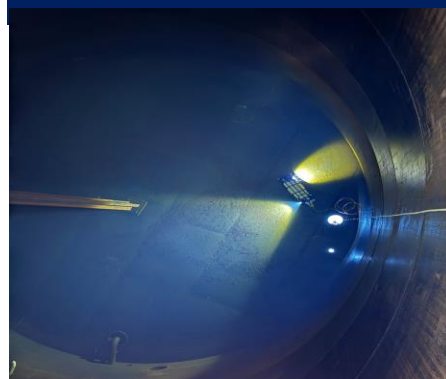
1. Mobilize



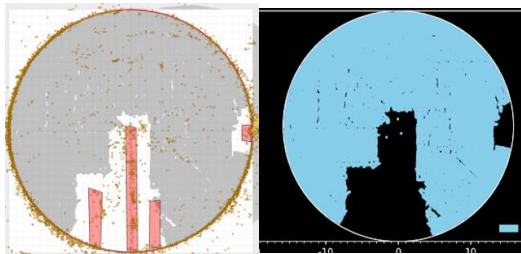
2. Lift



3. Submersion



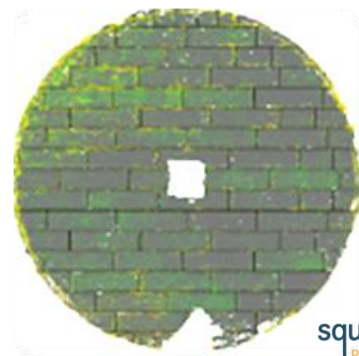
4. Inspection



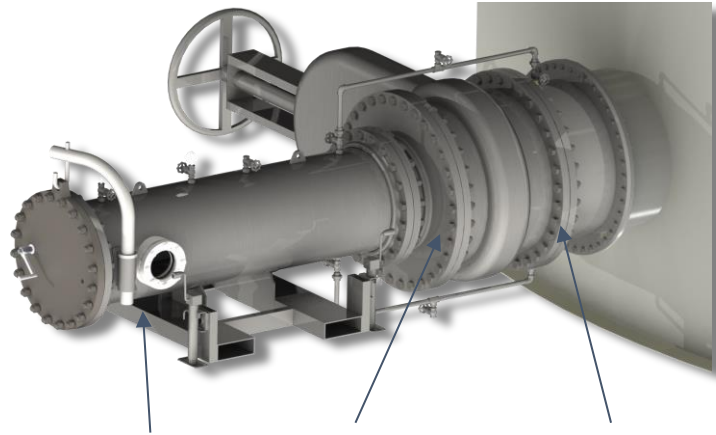
5. Recover



6. Report



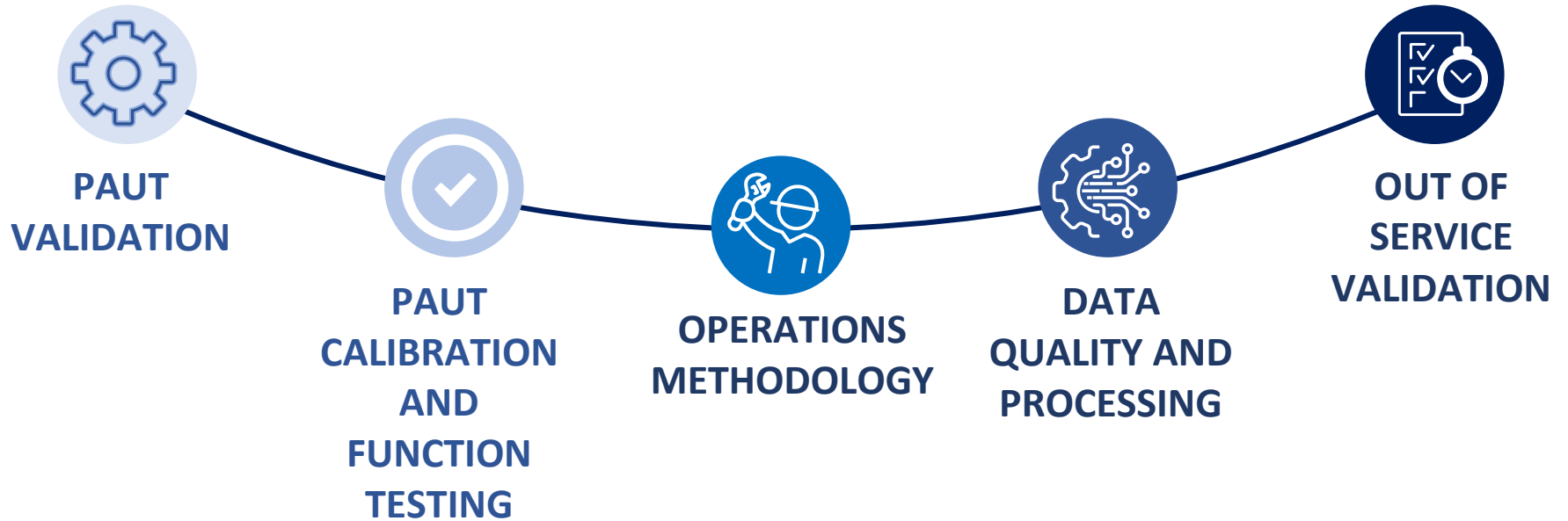
SR-3 Robot Side Launcher System



Vehicle Chamber **24" Gate Valve** **Manway Adapter**



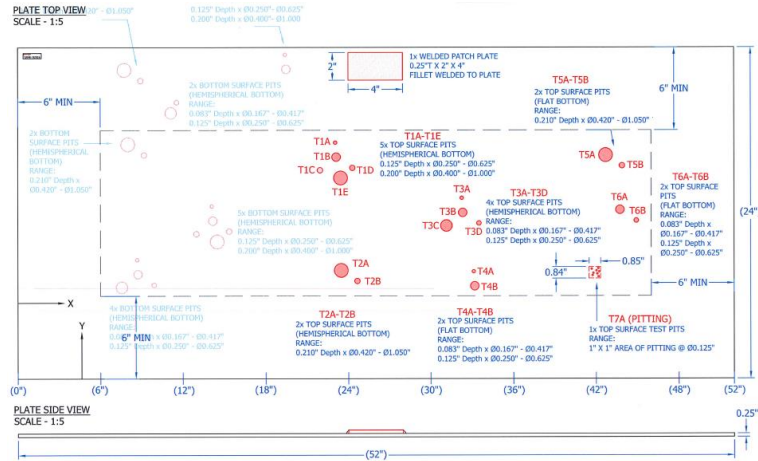
Maximizing Data Quality



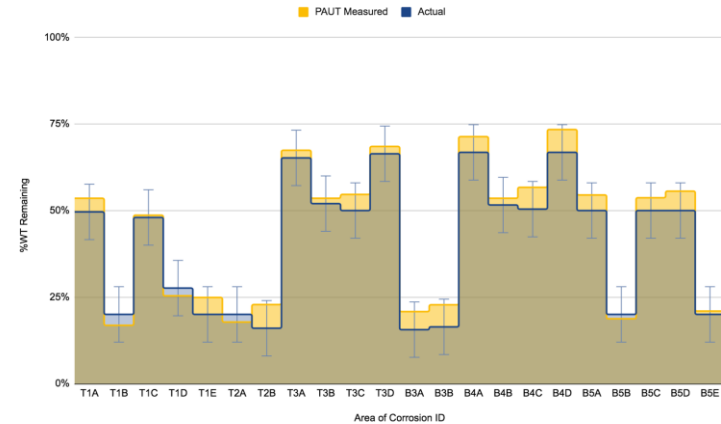
Phased Array UT Validation



API 653 Test Plates



Allowable Measurement Range Shown

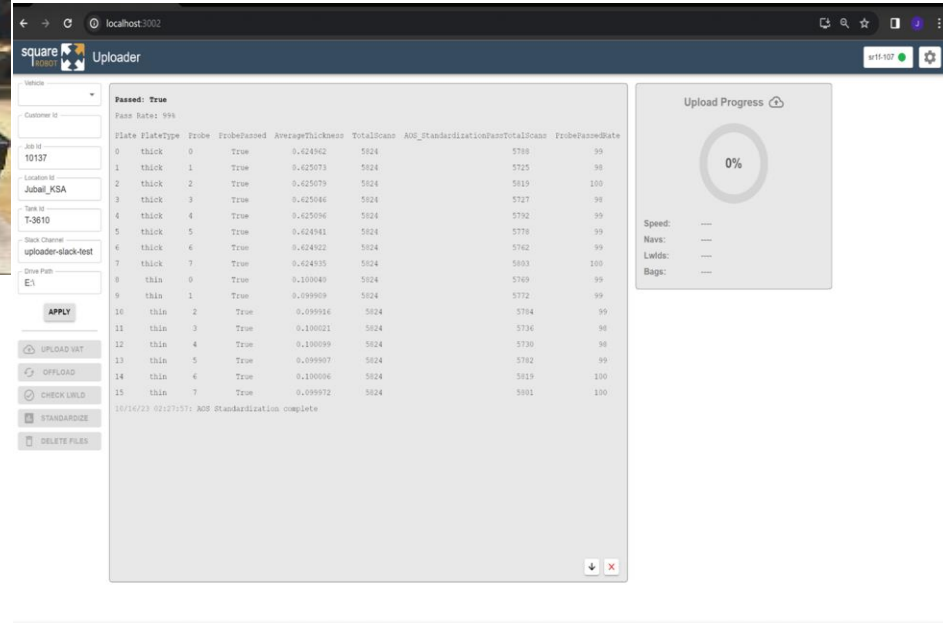
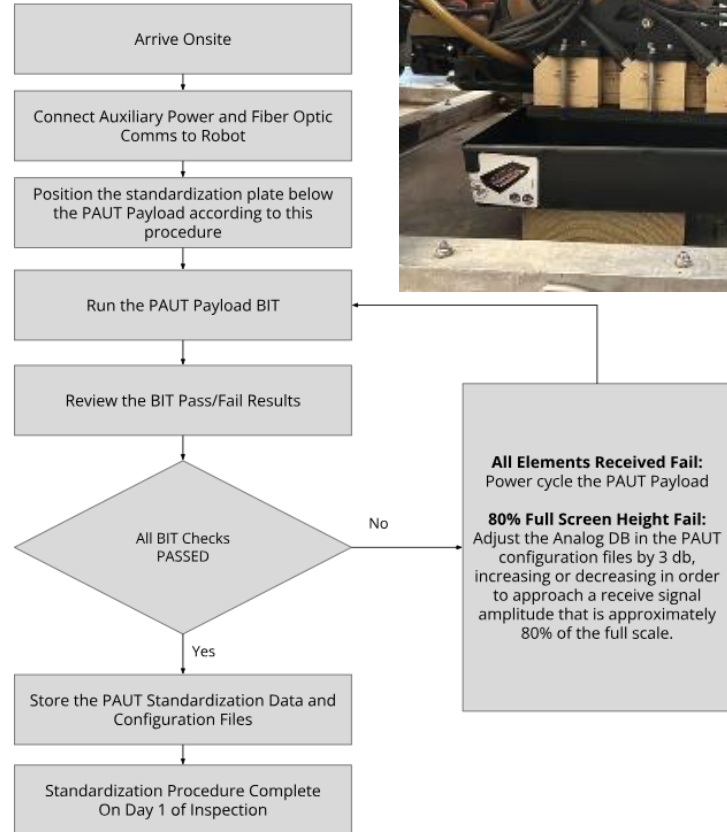


**Phased Array UT payload
Meets API 653 - Annex G Requirements**

PAUT Calibration/ Function Testing



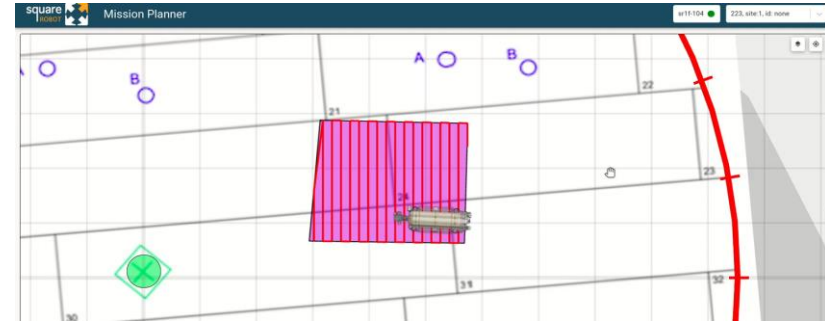
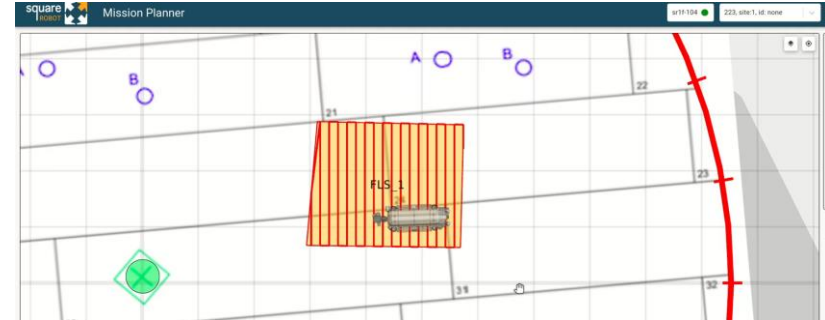
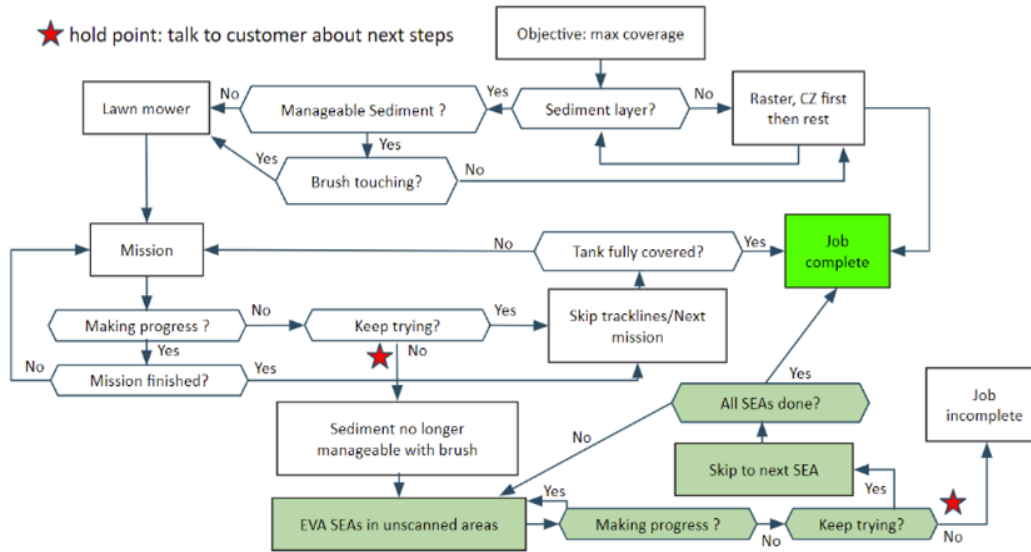
Flow Chart - On-Site



Operations Methodology - Onsite



★ hold point: talk to customer about next steps



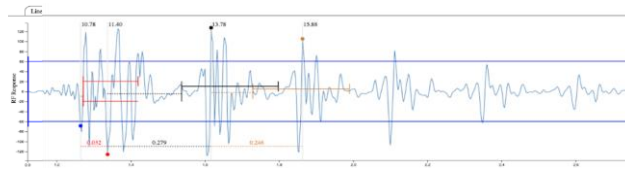
Data Quality and Processing



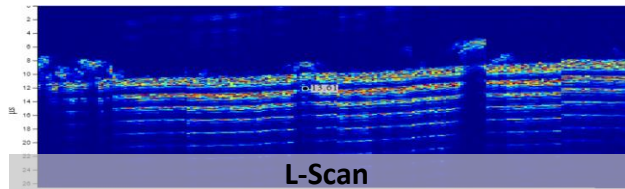
Heavily
attenuated signals



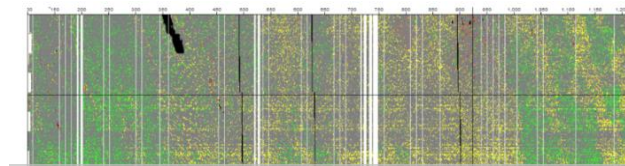
Heavily
attenuated signals



A-Scan

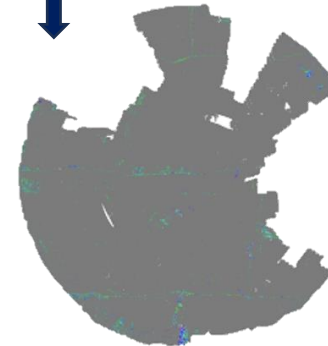
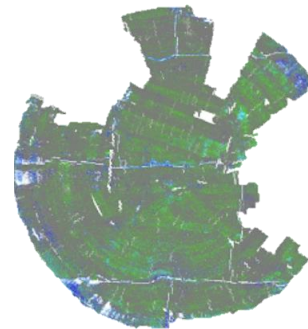


L-Scan



Linear View

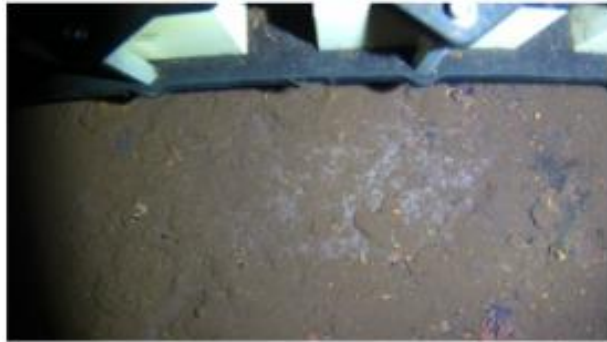
Post processing
thickness computation



PAUT Data Confirmation



Visual
Observations



IN-SERVICE
VIDEO/CAMERA FOOTAGE

Magnetic
Flux Leakage



OUT-OF-SERVICE
MFL SCANNING

Saturated Low
Frequency
Eddy Current



OUT-OF-SERVICE
SLOWFEC SCANNING

Continuous Improvement Feedback Loop

Case Study: 114' Diameter Diesel Tank

In-Service Robotic Inspection

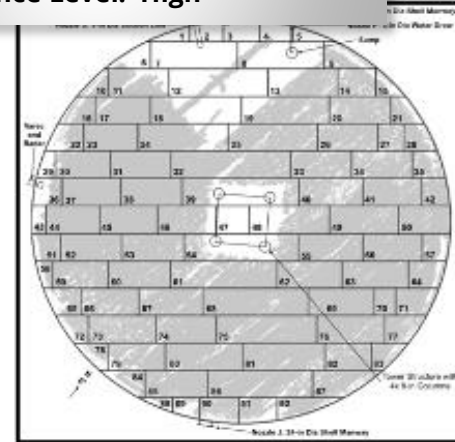
- Tank built 1978 with repairs in 2003
- Inspected while fueling train locomotives every 4 hours
- Water puddling
- Detected unknown double bottom

- Inspection Time: 3 DAYS
- UT Tank Bottom Coverage: 81%
- UT Plate Coverage: 90/94 plates
- Confidence Level: High

Savings: In-Service Robotic vs Traditional Inspection

~\$1.2 million USD vs Out of Service Inspection

- + ~40 days out of service time/temp storage
- + 6.6 tons of CO2 emissions contained
- + 670 confined space labor hours
- + Extended API 653 compliance 18 years with minor external repairs



Case Study: 92' Diameter Diesel Tank

In-Service Robotic Inspection

- Similar tanks nearby suggested repairs required
- Obtain API 653 compliant report
- Robotic inspection in 2022 to plan for 2025 repairs

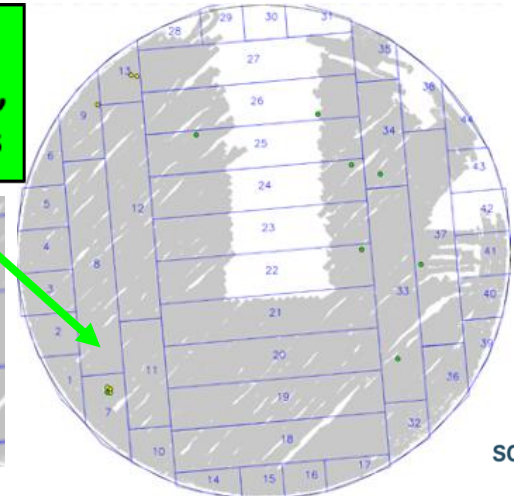
Savings: In-Service Robotic vs Traditional Inspection

- > **\$400k** vs Out of Service Inspection cost
- + **27 days** of out of service time
- + **5 tons** of CO2 emissions contained
- + **550** confined space labor hours
- + **Extended API 653 compliance > 20 years**

- Inspection Time: 3 DAYS
- UT Tank Bottom Coverage: 78%
- UT Plate Coverage: 29/31 plates
- Confidence Level: High



Plate 7D:
Soil side defect,
30.4% wall loss



Questions?



In-Service Tank Inspection Animation

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State of the Art Sensors

High Density Data Acquisition

